Exploring the assumptions of language acquisition models

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Midwest Speech & Language Days 2015



COGNIȚIVE COMPUȚAȚION GROUP





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- SLIDE> and not the reverse
- but it also needs to somehow figure out what parts of the scene are described in the utterance, namely that the girl is chasing the boy and not <SLIDE> that



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One way to formalise these interpretations is by using SRL, a shallow semantic representation, best described in the PropBank corpus annotation. In there, numbered labels indicate "proto-roles" like Agent, Patient, Recipient etc. and also Modifiers, like Locative Temporal etc.













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Multiple predicates



Here's another reason we need to know what the predicates are. As I already mentioned, the BabySRL is far from being a trivial dataset. And like a real child, our system is exposed to utterances with multiple predicates. The way we encode this information is to create a different proposition for each of the predicates (so for this sentence we have one proposition based on "remember", where "we" and "game" are both A1s, and a second proposition centred around "play" where "we" is now an A0, and "play" is an A1). And just to give you an idea of the significance of this, around a quarter of the corpus contains 2 verbs. So how does this affect the results of the system?

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This is what our second experiment focuses on. Without using any form of supervision, other than a few seed nouns, can we predict which words are predicates/ arguments? <SLIDE> This experiment can be viewed as test of one of the proposed mechanisms for Syntactic Bootstrapping (this is the hypothesis that children can infer at least part of the semantic interpretation of an utterance by using the syntactic patterns they observe), called Structure-Mapping. Structure-Mapping proposes that children are able to do that by mapping nouns to semantic arguments and using the number of arguments as a means to determine the frame of the predicate.



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The setup for this experiment is the following: we use an off-the-shelf HMM to induce 80 clusters, training on a large part of the CHILDES corpus. The HMM is given a list of some function words and clusters them separately. We also assume knowledge of some seed nouns; we generated a list of 76 known nouns from a questionnaire of language development reporting (from Dale and Ferguson). Our first and easiest task is to identify all noun clusters, using the simple heuristic that a cluster is labeled as a noun if it contains more than a specific threshold k number of seed nouns (for all the experiments in this talk we use k=4).



Our second task is the crucial one: identifying the verbs. We start by eliminating words that belong to either a Noun or a Function word state.



We are left with two candidates (with states 51 and 60). <SLIDE> Now we look at a histogram of argument-taking frequency for each candidate. This basically tells us that words in cluster 51 really like to co-occur with 2 arguments whereas cluster 60 prefers 1. <SLIDE> We therefore chose cluster 51 as the verb cluster. (this heuristic only returns the maximum probability candidate, based on the assumption that most sentences have a single verb predicate)



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We can see here, as expected, that as the number of seed nouns we use goes up, so does the performance of our argument heuristic. <SLIDE> The same is true for the verb heuristic, which significantly outperforms the random baseline <SLIDE> (this baseline uses the same exclusion methods as the predicate heuristic — known noun states and function words are excluded — and chooses a random cluster from the remaining candidates.



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However, behind this experiment lie a number of parameters, for which we need to either present a valid psycholinguistic account of why we are choosing a specific value, or explore their effect via experimentation. Some of these parameters are listed here. I will not go into details about every one, but we will be presenting a detailed account in our upcoming publication. I would like to focus on a couple of crucial parameters.



First, we need to look at our seed noun selection. The first set of results used a random subset for each number of seeds (averaged over 10 runs). But there is another source of information that we are not taking into account, and that is word frequency. If we sort the seed nouns by frequency <SLIDE> we see that even with as few as 24 nouns we can get the same performance as with the whole set of 76 nouns.



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A slightly more technical parameter has to do with the representation of our input. The original seed noun list (used by Connor et al.) was based on the "normalised" questionnaire of Dale and Fenson; this meant that the list contained on the singular form of words like "toe" or "toy" whereas most of the occurrences of those words in the corpus were in the plural. Other cases of normalisation had to do with different renderings of words like "mommy" or "dollie". If we include all these variants we see that we get a significant boost in our verb identification performance —reaching close to 95%.



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However, as you may remember from experiment 1, our corpus contains lots of utterances with multiple predicates. If instead of measuring the performance of our heuristic in terms of finding any verb in the utterance, we limit it to finding only the correct predicate each time <SLIDE> we see that the performance drops significantly, almost at the level of chance. However we see that the heuristic can learn if we limit our system to only using the first proposition of each utterance <SLIDE>.



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Conclusions

- BabySRL model of language acquisition
 - Evidence for syntactic bootstrapping
- Exploration of assumptions
 - Data representation
 - Evaluation

22

Psycholinguistic validity

In conclusion, I have presented the BabySRL model of language acquisition that, for the fist time, provides compelling evidence for the theory of syntactic bootstrapping. We explored a lot of the assumptions present in the input data, the system itself (and its evaluation) and I believe that this exploration will offer a psychologic validity to the parameter choices of this model.



Our first obvious next step is to combine the two experiments presented here, in an extension what Connor et al. called "BabySRL from scratch", where we go beyond single predicates (both verbal and prepositional) and where we relax the assumption of veridical top-down feedback using two different mechanisms (a superset of the gold labels or a simple animacy-based feedback, where the learned assigns the agent category to the animate object in the scene).



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