Exploring the assumptions of language acquisition models

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The task of language acquisition can be exemplified as follows:

- child observes a scene and hears an utterance
- it has to figure out that "boy" refers to the boy and "girl" to the girl
- "boy" and not the reverse
- but it also needs to somehow figure out what parts of the scene are described in the utterance, namely that the girl is chasing the boy and not "boy" that boy is running
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One way to formalise these interpretations is by using SRL, a shallow semantic representation, best described in the PropBank corpus annotation. In there, numbered labels indicate “proto-roles” like Agent, Patient, Recipient etc. and also Modifiers, like Locative Temporal etc.
Our work is based on the BabySRL corpus, created by Mike Connor and others at Illinois. It uses part of the CHILDES corpus and provides an SRL annotation of the adult utterances —slightly cleaned up to avoid parsing errors— with the focus being on verb predicates and the prototypical proposition in one with 1 verb and 2 noun arguments but notice that that's less than a 3rd of the total utterances, so it's not an easy corpus.

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Experiment 1: Supervised learning

Given **perfect feedback**, do simple, **bottom-level** features capture anything useful about semantic roles/verb preferences?
The setup we have is based on a supervised classifier, implemented using LBJava (really cool project), trained on the BabySRL corpus and tested on “novel verbs” like these, to mimic the experiments done with real infants (for the rest of the talk most of the results will be using the transitive case).
Experiment 1: Supervised learning

- Supervised classifier (average perceptron)
- LBJava [Rizzolo and Roth, 2010]
- Train on BabySRL corpus
- Test on novel verb sentences
  - Intransitive: “The bunny krads”
  - Transitive: “The boy krads the girl”
  - Ditransitive: “The girl krads the boy a bunny”

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The features we use reflect really obvious phenomena at the utterance level. We start with the “most frequent label” baseline (what it says on the tin), then we have

- the Lexical features, which are basically a concatenation of the predicate and the current argument glosses,
- the Noun Pattern features which simply encode the relative position of each noun and finally, the Verb Position features which rely on us knowing where the predicate is and record the position of each argument relative to that predicate.
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Here’s another reason we need to know what the predicates are. As I already mentioned, the BabySRL is far from being a trivial dataset. And like a real child, our system is exposed to utterances with multiple predicates. The way we encode this information is to create a different proposition for each of the predicates (so for this sentence we have one proposition based on “remember”, where “we” and “game” are both A1s, and a second proposition centred around “play” where “we” is now an A0, and “play” is an A1). And just to give you an idea of the significance of this, around a quarter of the corpus contains 2 verbs. So how does this affect the results of the system?
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If we focus on the NounPattern feature, this is the previous score, the one where all versions of the same sentence are used as input; and here <SLIDE> is the same classifier if we only keep the first proposition of every utterance and here <SLIDE> is if we keep the last. If this seems surprising, remember that the surface structure remains the same for the last setting. So we might get a feature like “4th out of 5 nouns” that still indicates an A0 (and little support for the 1st out of N nouns).
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Yes, but predicate knowledge is crucial

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Experiment 2: Unsupervised learning

Can we predict arguments/predicates using distributional clusters and a few seed nouns?

This is what our second experiment focuses on. Without using any form of supervision, other than a few seed nouns, can we predict which words are predicates/arguments? This experiment can be viewed as test of one of the proposed mechanisms for Syntactic Bootstrapping (this is the hypothesis that children can infer at least part of the semantic interpretation of an utterance by using the syntactic patterns they observe), called Structure-Mapping. Structure-Mapping proposes that children are able to do that by mapping nouns to semantic arguments and using the number of arguments as a means to determine the frame of the predicate.
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The setup for this experiment is the following: we use an off-the-shelf HMM to induce 80 clusters, training on a large part of the CHILDES corpus. The HMM is given a list of some function words and clusters them separately. We also assume knowledge of some seed nouns; we generated a list of 76 known nouns from a questionnaire of language development reporting (from Dale and Ferguson). Our first and easiest task is to identify all noun clusters, using the simple heuristic that a cluster is labeled as a noun if it contains more than a specific threshold \(k\) number of seed nouns (for all the experiments in this talk we use \(k=4\)).
Our second task is the crucial one: identifying the verbs. We start by eliminating words that belong to either a Noun or a Function word state.
We are left with two candidates (with states 51 and 60). Now we look at a histogram of argument-taking frequency for each candidate. This basically tells us that words in cluster 51 really like to co-occur with 2 arguments whereas cluster 60 prefers 1. We therefore chose cluster 51 as the verb cluster. (this heuristic only returns the maximum probability candidate, based on the assumption that most sentences have a single verb predicate)
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We can see here, as expected, that as the number of seed nouns we use goes up, so does the performance of our argument heuristic. The same is true for the verb heuristic, which significantly outperforms the random baseline (this baseline uses the same exclusion methods as the predicate heuristic — known noun states and function words are excluded — and chooses a random cluster from the remaining candidates.)
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Experiment 2: Parameters

- Random/frequent seed noun selection
- Variants + plurals of seed nouns
- Verb/predicate evaluation
- Multiple predicates
- Seed noun threshold $k$
- Null predictions
- Function words

However, behind this experiment lie a number of parameters, for which we need to either present a valid psycholinguistic account of why we are choosing a specific value, or explore their effect via experimentation. Some of these parameters are listed here. I will not go into details about every one, but we will be presenting a detailed account in our upcoming publication. I would like to focus on a couple of crucial parameters.
First, we need to look at our seed noun selection. The first set of results used a random subset for each number of seeds (averaged over 10 runs). But there is another source of information that we are not taking into account, and that is word frequency. If we sort the seed nouns by frequency, we see that even with as few as 24 nouns we can get the same performance as with the whole set of 76 nouns.
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However, as you may remember from experiment 1, our corpus contains lots of utterances with multiple predicates. If instead of measuring the performance of our heuristic in terms of finding any verb in the utterance, we limit it to finding only the correct predicate each time, we see that the performance drops significantly, almost at the level of chance. However, we see that the heuristic can learn if we limit our system to only using the first proposition of each utterance.
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Yes, with as few as 24 seed nouns need to consider multiple predicates

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In conclusion, I have presented the BabySRL model of language acquisition that, for the first time, provides compelling evidence for the theory of syntactic bootstrapping. We explored a lot of the assumptions present in the input data, the system itself (and its evaluation) and I believe that this exploration will offer a psychologic validity to the parameter choices of this model.
Future Directions

- BabySRL from scratch [Connor et al. 2012]
- Beyond single predicates
  - Multiple verbs
  - Prepositions
- Relaxing perfect feedback (scene ambiguity)
  - Superset
  - Bootstrapped Animacy

Our first obvious next step is to combine the two experiments presented here, in an extension what Connor et al. called “BabySRL from scratch”, where we go beyond single predicates (both verbal and prepositional) and where we relax the assumption of veridical top-down feedback using two different mechanisms (a superset of the gold labels or a simple animacy-based feedback, where the learned assigns the agent category to the animate object in the scene).
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